# Package 'DEPONS2R'

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ais.to.DeponsShips Convert ship tracks to DeponsShips object

#### **Description**

Convert Automatic Identification System (AIS) data for ships to ship track objects. This is done by cropping one or more ship tracks to the extent of a landscape and converting the data to a DeponsShips-class object. If the AIS data does not include ship positions recorded in half-hour steps, the tracks are interpolated to make objects suitable for use in DEPONS.

#### Usage

```
ais.to.DeponsShips(data, landsc, title = "NA", ...)
```

### **Arguments**

data	data.frame with ship positions and the times at which the positions were recorded. Must contain the columns 'id', 'time' (of the form " type, character), 'length' (ship length, meters), 'x', and 'y' (position, meters/UTM).
landsc	A DeponsRaster object corresponding to the landscape that the ships move in. It is assumed that the spatial projection of the ship positions corresponds to that of the DeponsRaster object
title	Title of the output object
• • •	Optional parameters, including 'startday' and 'endday' (" from 'data'. If startday = endday the output object will contain up to 49 positions from the selected date for each vessel track.

### Value

Returns a DeponsShips object containing one or more ships assigned to each of the routes in the object. All ships on a particular route move at the same speed along the route. The routes are defined by x and y coordinates based on the same coordinate reference system as the landscape they are located in. The speed that ships use after reaching a particular position (a particular 'virtual buoy') is calculated from the distance to the following position, and the time it takes reaching that position. If speed is included in the input AIS data, this is NOT used. The routes include one position per half-hour time step, corresponding to the default time step used in the DEPONS model. If input data does not include one position per half hour, new positions are generated using linear interpolation. If the input data contains many positions in a particular half-hour interval, only the positions closest to the half-hour interval are used. The routes contain information about the number of half-hour intervals were ships 'pause' at a particular location, e.g. in a port. These are calculated based on the input AIS data.

4 aisdata

#### See Also

aisdata for an example of data that can be used as input to ais.to.DeponsShips. The function builds on interpolate.ais.data, which interpolates tracks to ensure that there is a position every 30 minutes. Use check.DeponsShips for testing if speeds are realistic. See write.DeponsShips for conversion of DeponsShips objects to json-files to be used in DEPONS. Use routes, ships, and title for inspection/modification of the ship tracks.

### **Examples**

```
data(aisdata)
plot(aisdata$x, aisdata$y, type="n", asp=1)
ids <- sort(unique(aisdata$id))</pre>
my.colors <- heat.colors(length(ids))</pre>
for (i in 1:length(ids)) {
 id <- ids[i]</pre>
 points(aisdata$x[aisdata$id==id], aisdata$y[aisdata$id==id],
     cex=0.6, col=my.colors[i])
}
data(bathymetry)
plot(bathymetry, add=TRUE)
depons.ais <- ais.to.DeponsShips(aisdata, bathymetry)</pre>
the.routes <- routes(depons.ais)</pre>
for (i in 1:length(ids)) {
points(the.routes[[i]]$x, the.routes[[i]]$y,
        cex=0.6, pch=16, col=my.colors[i])
depons.ais <- ais.to.DeponsShips(aisdata, bathymetry,</pre>
   startday="2015-12-20", endday="2015-12-20")
routes(depons.ais)
aisdata2 <- aisdata
aisdata2$time <- format(as.POSIXct(aisdata$time)+300)</pre>
depons.ais2 <- ais.to.DeponsShips(aisdata2, bathymetry,</pre>
                                 startday="2015-12-20", endday="2015-12-21")
routes(depons.ais2)
```

aisdata

Position for three ships in the inner Danish waters

### Description

Automatic identification system (AIS) data for three ships in Kattegat and the Western Baltic from 20 Dec 2015. The data set includes the variables id (the Maritime Mobile Service Identity number), time, speed (in knots), type, length (in metres), x and y (which provide the coordinates of the ship at a given time. The coordinates use the UTM zone 32 projection (CRS = "+proj=utm +zone=32 +units=m +no\_defs +datum=WGS84").

#### **Format**

data.frame

```
as.data.frame,DeponsDyn-method
```

Convert DeponsDyn object to data frame

# **Description**

Function for converting DEPONS population dynamics object to a data frame.

### Usage

```
## S4 method for signature 'DeponsDyn'
as.data.frame(x, row.names = NULL, optional = FALSE, ...)
```

### **Arguments**

x DeponsDyn object

row.names NULL or a character vector giving the row names for the data frame. Missing

values are not allowed.

optional Logical (not used)

... additional arguments to be passed to or from methods.

### Value

```
data.frame object
```

# **Examples**

```
data(porpoisedyn)
class(porpoisedyn)
the.dyn <- as.data.frame(porpoisedyn)</pre>
```

```
as.data.frame,DeponsTrack-method
```

Convert DeponsTrack to data frame

# Description

Function for converting DEPONS movement track file to a data frame.

### Usage

```
## S4 method for signature 'DeponsTrack'
as.data.frame(x, row.names = NULL, optional = FALSE, ...)
```

6 bathymetry

# **Arguments**

x DeponsTrack object

row.names NULL or a character vector giving the row names for the data frame. Missing

values are not allowed.

optional Logical (not used)

. . . additional arguments to be passed to or from methods.

### Value

data.frame object

### **Examples**

```
data(porpoisetrack)
class(porpoisetrack)
the.track <- as.data.frame(porpoisetrack)</pre>
```

bathymetry

Bathymetry of the Kattegat area

### **Description**

The standard bathymetry file for Kattegat which is used in DEPONS simulations. It is based on a raster file with 1000 rows and 600 columns where each grid cell corresponds to 400 m x 400 m. Cells on land are assigned a missing data value of -9999.

The Kattegat landscapes use the UTM zone 32 projection, (EPSG:32632) as in the study by Nabe-Nielsen et al (2014). The corresponding proj4string is "+proj=utm +zone=32 +datum=WGS84 +units=m +no\_defs" (see https://epsg.io/32632).

### **Format**

DeponsRaster

#### References

Nabe-Nielsen, J., Sibly, R. M., Tougaard, J., Teilmann, J., & Sveegaard, S. (2014). Effects of noise and by-catch on a Danish harbour porpoise population. Ecological Modelling, 272, 242–251. doi:10.1016/j.ecolmodel.2013.09.025

### See Also

DeponsRaster-class

bbox 7

bbox Get bbox from Depons\* object

# Description

Retrieves spatial bounding box from object. If a Depons\* object is a DeponsTrack object containing multiple track, the box bounds all tracks.

### Usage

```
## S4 method for signature 'DeponsRaster'
bbox(obj)
## S4 method for signature 'DeponsTrack'
bbox(obj)
```

### **Arguments**

obj

DeponsRaster or DeponsTrack object

#### Value

Returns a matrix defining the northern, southern, eastern and western boundary of a DeponsRaster object or of one or more DeponsTrack objects.

### See Also

```
make.clip.poly
```

calib\_01

Plot distribution of turning angles, step lengths and speed of tracked simulated porpoises.

### **Description**

Plot distribution of turning angles, step lengths and speed of tracked simulated porpoises.

# Usage

```
calib_01(depons_track)
```

# **Arguments**

depons\_track Object of class 'DeponsTrack' produced by either read.DeponsTrack or read.DeponsTrackBatch

8 check.DeponsShips

# Value

Plot histograms of turning angles, step length and speed. It also stores those metrics of the animal in a dataframe.

check.DeponsShips Check if ships move at unrealistic speeds or are outside the map boundary

# **Description**

Checks if calculated speeds in DeponsShips objects are unrealistic, which may result from inaccurate AIS positional records or from ships leaving the map area, then re-entering at a remote position. As ship speed in DEPONS directly influences the amount of noise generated, it is advisable to detect and remove such instances to avoid the creation of extreme noise sources. The function can also repair issues arising from ship positions that are a fraction of a meter outside the map boundary (causing loading errors on simulation start).

### Usage

```
check.DeponsShips(
   x,
   threshold = 35,
   fix = F,
   replacements = NA,
   landscape = NULL
)
```

### **Arguments**

X	DeponsShips object
threshold	The speed (knots) above which calculated values are considered unrealistic/excessive. Defaults to $35\ knots$ .
fix	Logical. If FALSE (default), the function returns a data frame of ship tracks containing speeds that exceed the threshold; if TRUE, the function returns a DeponsShips object where these instances have been replaced.
replacements	Named list, where names are ship types and values are replacement speeds (knots) for speeds above the threshold within those types. Only ship types named in the list are processed. If NA (default), reference speeds from Table 1 in MacGillivray & de Jong (2021) are used.
landscape	DeponsRaster object. Optional; a map representative of the simulation map extent (usually the bathymetry map). If provided and fix = TRUE, ship positions on the boundary will be adjusted to avoid errors from fractional mis-positioning.

coastline

#### **Details**

The default replacement speeds (knots) for recognized ship types are as follows (class reference speeds from MacGillivray & de Jong, 2021, Table 1): Fishing, 6.4; Tug, 3.7; Naval, 11.1; Recreational, 10.6; Government/Research, 8; Cruise, 17.1; Passenger, 9.7; Bulker, 13.9; Containership, 18.0; Tanker, 12.4; Dredger, 9.5; Other, 7.4.

If a simulation fails during data loading with an error that indicates ship positions outside the simulation area, this may be caused by a mismatch in rounding between the map extent of the map used with ais.to.DeponsShips, and of generated ship position exactly on the boundary. If a map representative of the simulation area extent is provided (usually the bathymetry map), the function will also repair these positions by rounding them up/down to the floor/ceiling of the map extent (fractional meter adjustments).

### Value

If fix = FALSE, a data frame with columns "route number", "name", "type", "length", and "speed", containing one entry for each ship where an excessive speed occurred. If fix = TRUE, a DeponsShip object where instances of excessive speed have been replaced, and (if a map has been provided) where ship positions on the boundary have been adjusted.

#### Reference

MacGillivray, A., & de Jong, C (2021). A reference spectrum model for estimating source levels of marine shipping based on Automated Identification System data. Journal of Marince Science and Engineering, 9(4), 369. doi:10.3390/jmse9040369

### See Also

ais.to.DeponsShips for creation of DeponsShips objects (including calculated speeds) from AIS data

#### **Examples**

```
## Not run:
x <- shipdata
check.DeponsShips(x)

x@routes$route[[1]]$speed <- x@routes$route[[1]]$speed * 3
check.DeponsShips(x)
x <- check.DeponsShips(x, fix = T)
## End(Not run)</pre>
```

coastline

Coastline of Northern Europe

10 crs

### **Description**

An object of class SpatialPolygonsDataFrame showing the coastline of the North Sea, Kattegat, and the Western Baltic. The map projection used is ETRS89 – EPSG:3035 projection as for the North Sea raster files used by DEPONS. The corresponding proj4string is "+proj=laea +lat\_0=52 +lon\_0=10 +x\_0=4321000 +y\_0=3210000 +datum=WGS84 +units=m +no\_defs".

#### **Format**

SpatialPolygonsDataFrame

crs

Get or set map projection in Depons\* objects

### **Description**

Get or set the map projection (also known as coordinate reference system, crs) of DeponsRaster and DeponsTrack objects.

# Usage

```
## S4 method for signature 'DeponsTrack'
crs(x)

## S4 method for signature 'DeponsShips'
crs(x)

## S4 method for signature 'DeponsRaster'
crs(x)

## S4 replacement method for signature 'DeponsTrack'
crs(x) <- value

## S4 replacement method for signature 'DeponsShips'
crs(x) <- value

## S4 replacement method for signature 'DeponsRaster'
crs(x) <- value</pre>
```

### **Arguments**

x Object of class class DeponsRaster, DeponsShips or DeponsTrackvalue (proj4string) identifying the map projection

DEPONS2R

DEPONS2R

Package for analyzing DEPONS simulation output

#### **Description**

Methods for analyzing population dynamics and movement tracks simulated using the DEPONS model (v.3.0; https://www.depons.eu), for manipulating input raster files, shipping routes and for analyzing sound propagated from ships.

The classes used in DEPONS2R include:

- DeponsTrack movement tracks, read from "RandomPorpoise.XXX.csv" files
- DeponsDyn population dynamics data, from "Statistics.XXX.csv" files
- DeponsBlockdyn data from "PorpoisePerBlock.XXX.csv" files
- DeponsShips data from "ships.json" files or from AIS data

Here the DeponsDyn data include both changes in population size and energetics through time for the entire landscape, whereas DeponsBlockdyn data include variations in population size in different parts (or 'blocks') of the landscape. XXX is the date and time when the simulation was finished.

DeponsBlockdyn-class DeponsBlockdyn-class

# Description

Stores objects containing population size for different parts of the landscape (i.e. different 'blocks')

#### **Details**

The dyn slot contains a data frame with the columns 'tick', which indicates the number of half-hourly time steps since the start of the simulation; a column 'block' indicating the region of the landscape where animals were counted, a 'count' column with the number of animals in that block and tick. The 'real.time' column shows the real-world equivalent to 'tick, i.e. the time that has passed since 'startday'.

### **Slots**

title Character. Name of the object or simulation

landscape Character. Identifier for the landscape used in the DEPONS simulations. The landscapes 'DanTysk', 'Gemini', 'Kattegat', 'North Sea', 'Homogeneous', and 'User defined' are distributed with the DEPONS model.

simtime POSIX1t object with the date and time when the simulation was finished. This is read from the name of the imput file.

startday POSIXIt object with the first day of the simulation, i.e. the first day in the period that the simulations are intended to represent in the real world.

dyn Data frame with simulation output.

12 DeponsDyn-class

#### Note

DeponsBlockdyn-objects are usually read in from csv files produced during DEPONS simulations. These files are named 'PorpoisePerBlock.XXX.csv', where XXX indicates the date and time when the simulation was finished.

#### See Also

plot.DeponsBlockdyn and read.DeponsBlockdyn.

### **Examples**

```
a.DeponsBlockdyn <- new("DeponsBlockdyn")
a.DeponsBlockdyn</pre>
```

DeponsDyn-class

DeponsDyn-class

### **Description**

Stores objects containing population dynamics output and energetic output simulated using the DEPONS model.

#### **Details**

The following columns are included in the simulation output data frame: 'tick', which indicates the number of half-hourly time steps since the start of the simulation; 'count', which indicates the population size at a given time; 'anim.e', showing the average amount of energy stored by simulated animals; 'lands.e', which shows the total amount of energy in the landscape, and 'real.time' which shows the time relative to 'startday'.

#### Slots

title Character. Name of the object or simulation

landscape Character. Identifier for the landscape used in the DEPONS simulations. The land-scapes 'DanTysk', 'Gemini', 'Kattegat', 'North Sea', 'Homogeneous', and 'User defined' are distributed with the DEPONS model.

simtime POSIX1t object with the date and time when the simulation was finished. This is read from the name of the imput file.

startday POSIXIt object with the first day of the simulation, i.e. the first day in the period that the simulations are intended to represent in the real world.

dyn Data frame with simulation output.

#### Note

DeponsDyn-objects are usually read in from csv files produced during DEPONS simulations. These files are named 'Statistics.XXX.csv', where XXX indicates the date and time when the simulation was finished.

DeponsRaster-class 13

### See Also

plot.DeponsDyn and read.DeponsDyn.

### **Examples**

```
a.DeponsDyn <- new("DeponsDyn")</pre>
```

a.DeponsDyn

DeponsRaster-class

DeponsRaster-class

#### **Description**

Stores objects containing raster landscapes used as input in DEPONS simulations.

#### **Slots**

type Character. Identifies the kind of data stored in the raster; should be 'food', 'patches', bathymetry', 'dtc', 'salinity', 'blocks' or 'NA'.

landscape Character Identifier for the landscape used in the DEPONS simulations. The land-scapes 'DanTysk', 'Gemini', 'Kattegat', 'North Sea', 'Homogeneous', and 'User defined' are distributed with the DEPONS model.

crs Object of class "CRS", i.e. the coordinate reference system. This is provided as a proj4string text string.

header Data frame with data on number of columns and rows in the input raster, the coordinates of the lower left corner, the size of each grid cell and the integer value used to represent missing data

ext Data frame with the extent of the landscape.

data The actual data values for each of the grid cells.

### Note

DeponsRaster-objects are typically read in from ascii raster files that have been used for DEPONS simulations.

#### See Also

plot.DeponsRaster, read.DeponsRaster and make.blocksraster. bathymetry is an example of a DeponsRaster-object.

#### **Examples**

```
a.deponsraster <- new("DeponsRaster")</pre>
```

a.deponsraster

14 DeponsTrack-class

DeponsShips-class

DeponsShips-class

### **Description**

Objects containing ship routes and ships

Methods for manipulating, plotting and analyzing ship routes and ship agents used in DEPONS simulations.

#### Slots

```
title Name of the object (character)
```

landscape Name of the landscape that the ships occur in (character)

crs CRS object providing the coordinate reference system used; see CRS for details

routes data. frame geographic positions of the 'virtual buoys' that define one or more ship routes that ship agents follow, and the speed that the ships should use when following this route. They also provide information about how long ships should use speed zero when reaching a specific buoy ('i.e. 'pause', measured in minutes). Can be extracted using the routes function.

ships data.frame defining each of the ships occurring in DEPONS simulations, and the routes they occur on. The data frame includes the variables 'name', 'type', 'length', and 'route'. Info can be extracted using the ships function.

### See Also

```
plot.DeponsShips, and read.DeponsShips
```

### **Examples**

```
data(shipdata)
ships(shipdata)[1:10,]
routes(shipdata)
plot(shipdata, col=c("red", "purple", "blue"))
```

DeponsTrack-class

DeponsTrack-class

### **Description**

Stores objects containing animal movement tracks simulated using the DEPONS model Classes for manipulating and plotting movement tracks generated with DEPONS.

dyn 15

### **Slots**

```
title Name of the object (character)
landscape Name of the object (character)
```

simtime POSIXIt object with the date and time when the simulation was finished. This is read from the name of the imput file.

crs CRS object providing the coordinate reference system used; see st\_crs for details

tracks Listwith one or more tracks, each stored as a SpatialPointsDataFrame object)

#### See Also

plot.DeponsTrack and read.DeponsTrack

dyn

Extract population dynamics from objects

### **Description**

Extract population dynamics from objects

# Usage

```
## S4 method for signature 'DeponsDyn'
dyn(x)

## S4 method for signature 'DeponsBlockdyn'
dyn(x)
```

### **Arguments**

Χ

Object of class DeponsBlockdyn.

get.latest.sim

Get name of newest file

# Description

Returns the name of the newest simulation output of a particular type within the specified directory. The date and time are extracted from the file name.

# Usage

```
get.latest.sim(type = "dyn", dir)
```

16 get.simtime

### **Arguments**

type Type of simulation output to check; can be one of: "dyn" (for looking in "Statis-

tics.XX.csv" files), "blockdyn" (for looking in "PorpoisePerBlock.XX.csv" files)

"track" (for looking in "RandomPorpoise.XX.csv" files).

dir Directory to look for simulation output in (character string)

### Value

character string with the name of the most recent simulation output file.

### See Also

read. DeponsBlockdyn for example.

get.simtime

Get simulation date

### Description

Returns the date and time when a specific simulation was finished, obtained from the date stored as part of the file name. The date format is system dependent, but the function attemts to extract the data assuming that either the English or the local language is used. (a POSIX1t object)

### Usage

```
get.simtime(fname = NULL, tz = "UTC")
```

### **Arguments**

fname Character string with name of the file to extract the simulation date from, in-

cluding the path

tz Time zone

### Value

Returns a POSIX1t object

#### See Also

```
get.latest.sim
```

interpolate.ais.data 17

### Description

Interpolates ship movement tracks obtained from Automatic Identification System (AIS) data to obtain exactly one position per 30 minutes. The first and last position in the original track are omitted unless minutes = 0 or 30 and seconds = 0.

# Usage

```
interpolate.ais.data(aisdata)
```

### **Arguments**

aisdata

Data frame including the columns 'id' (ship identifier), 'time' (text string readable by as.POSIXct), 'x' and 'y' (recorded ship position, unit: meters), and potentially additional columns

### Value

Returns a data frame with the same columns as the input data. Tracks that are too short to interpolate are omitted (with a warning)

# See Also

```
read.DeponsShips and ais.to.DeponsShips
```

18 make.blocksraster

landscape<-

Get or set the landscape name

### **Description**

Get or set the landscape name Get or set the landscape name

### Usage

```
## S4 replacement method for signature 'DeponsTrack'
landscape(x) <- value

## S4 method for signature 'DeponsTrack'
landscape(x)

## S4 replacement method for signature 'DeponsDyn'
landscape(x) <- value

## S4 method for signature 'DeponsDyn'
landscape(x)

## S4 replacement method for signature 'DeponsBlockdyn'
landscape(x) <- value

## S4 method for signature 'DeponsBlockdyn'
landscape(x)</pre>
```

### **Arguments**

x Object of class DeponsBlockdyn.value Name of the landscape (character)

make.blocksraster

Makes new file with blocks

### **Description**

Produces a DeponsRaster object of type='blocks' for use in DEPONS simulations. This allows animals to be counted within specific regions (blocks) of the landscape during the simulation. The new blocks can be specified as either matrices or SpatialPolygons objects. For matrices, the blocks are defined as the smallest rectangle that includes all the specified positions.

make.blocksraster 19

### **Usage**

```
## S4 method for signature 'DeponsRaster'
make.blocksraster(
  template,
  blocks = NA,
  blockvals = NULL,
  NAvalue = -9999,
  plot = FALSE,
  fname = NULL,
  overwrite = FALSE
)
```

### **Arguments**

template DeponsRaster object used as template for new blocks file

blocks list of areas to be used for new blocks. Each item in 'blocks' should be a matrix

(with two columns, corresponding to x- and y-coordinates) or a SpatialPolygons

object

blockvals Vector of integer values defining the labels of the new blocks. The first value de-

fines the background value, so the length of 'blockvals' should equal the number

of blocks plus 1

NAvalue Value used for missing data in the output object

plot If TRUE, the raster block is plotted

fname Name of the output raster file (character string ending with '.asc'). No file is

written to disk if fname is not provided.

overwrite Whether to replace existing file.

### Value

RasterLayer object defining different subregions of the landscape where animals should be counted.

#### Note

The blocks file should not be modified when running DEPONS simulations using the 'Kattegat' landscape. In this landscape the simulated animals use the blocks file for navigation. Also note that blocks are added to the new blocks raster in the order they are file in the order in which they are listed in 'blocks', so the order mattes if the blocks overlap.

```
#Load file to use as template for new blocks file
data("bathymetry")

# Make list of blocks to create
new.blocks <- list()
x <- runif(8, 700000, 760000)
y <- runif(8, 6200000, 6300000)
new.blocks[[1]] <- cbind(x,y)</pre>
```

20 make.clip.poly

```
x <- c(600000, 635000, 670000, 635000)
y <- c(6150000, 6200000, 6150000, 6100000)
library(sp)
srl <- list(Polygon(cbind(x,y)))
Srl <- list(Polygons(srl, ID=as.vector("p")))
new.blocks[[2]] <- SpatialPolygons(Srl, proj4string=crs(bathymetry))
make.blocksraster(bathymetry, new.blocks, plot=TRUE)
points(new.blocks[[1]])
plot(new.blocks[[2]], add=TRUE)

the.dir <- tempdir()
make.blocksraster(bathymetry, new.blocks, fname=paste0(the.dir, "/test.asc"))</pre>
```

make.clip.poly

Make clipping polygon from bbox

# Description

Makes a polygon from a bounding box to use for clipping the coastline, or other SpatialPolygons objects

### Usage

```
## S4 method for signature 'matrix'
make.clip.poly(bbox, crs)
```

### Arguments

bbox 2x2 matrix

crs CRS object defining the projection of the SpatialPolygons object to be clipped

#### Value

SpatialPolygons object

### See Also

bbox for creation of bbox matrix from DeponsRaster

```
data(bathymetry)
bbox <- cbind("min"=c(549517, 6155000), "max"=c(636000, 6210000))
rownames(bbox) <- c("x", "y")
clip.poly <- make.clip.poly(bbox, crs(bathymetry))</pre>
```

make.DeponsDyn 21

make.DeponsDyn	Make DeponsDyn object from data stored in data frame
----------------	--

# Description

Function for reading converting a data frame containing DEPONS simulation output to a Depons-Dyn object.

# Usage

```
make.DeponsDyn(
  oname,
  title = "NA",
  landscape = "NA",
  simtime = "NA",
  startday = "2000-01-01",
  timestep = 30,
  tz = "UTC"
)
```

# Arguments

oname	Name of the object (data frame) that contains number of animals for each time step during the simulation, along with their energy and the amount of food in the landscape.
title	Optional character string giving name of simulation
landscape	The landscape used in the simulation
simtime	Optional character string with the date and time when the simulation finished (format yyyy-mm-dd).
startday	The start of the period that the simulation represents, i.e. the real-world equivalent of 'tick 1' (character string of the form 'yyyy-mm-dd', or POSIXIt). Defaluts to 2000-01-01 (UTC time).
timestep	Time step used in the model, in minutes. Defaults to 30 minutes in DEPONS.
tz	Time zone.

### Value

DeponsDyn object containing simulation output

### See Also

See DeponsDyn-class for details on what is stored in the output object.

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### **Examples**

```
data(porpoisedyn)
the.data <- as.data.frame(porpoisedyn)
the.data <- the.data[, c(1:4)]
names(the.data) <- c("tick", "PorpoiseCount", "FoodEnergyLevel", "PorpoiseEnergyLevel")
porpoisedyn2 <- make.DeponsDyn(the.data, startday="2010-01-01")
porpoisedyn2</pre>
```

### **Description**

Identifies ship positions in a DeponsShips object where the ship is stationary (pausing) but potentially still actively using its engine (bollard pushing or using dynamic positioning system), and if desired assigns a suitable non-zero speed to ensure noise generation at that time point. Candidates may be found either among all ships that are at a minimum distance from shore, or among those that are close to specific structures of interest, such as wind turbines.

### Usage

```
make.stationary.ships(
    X,
    action = "check",
    candidates = NULL,
    distcrit = "shore",
    landscape = NULL,
    structure_locations = NULL,
    start_day = NA,
    start_times = NULL,
    verbose = F
)
```

### Arguments

х	DeponsShips	object
---	-------------	--------

action Character. If "check" (default), returns a data frame of pause positions that are

candidates for stationary activity based on the selected criteria. If "replace" and a candidates data frame is provided, returns a DeponsShip object where the pauses identified in the data frame have been converted to stationary active status (i.e.,

a non-zero speed has been assigned)

candidates A data frame of pause positions that are candidates for stationary activity. Re-

quired if 'action = "replace"'. Generated by using 'action = "check"'

make.stationary.ships 23

distcrit

Character. Main criterion for finding candidates for stationary activity. If "shore" (default), all ship positions in open water are eligible, subject to a number of secondary criteria (see Details). In this case, a DeponsRaster must be provided that allows determination of distance from land (see below). If any other value or NA, only ship positions close to specified structure locations (such as turbine piles) are eligible, and these locations must be provided via 'structure\_locations' (see below). In this case, a start day for the ship records and individual start times for the structure locations may also be provided to allow simulation of an ongoing construction process (see below)

landscape

A DeponsRaster where land areas are indicated as NA (e.g., the prey map for the simulation). Required if 'distcrit = "shore" to determine distance of candidate positions from land

structure\_locations

A data frame with columns "id", "x" (numerical) and "y" (numerical), and one row for each structure that is to be used as a proximity criterion for finding candidates. Required if distcrit != 'shore'

start\_day A character string or POSIX object of the form 'YYYY-MM-DD HH:MM:SS'.

Defines the start time of x. Optional; can be provided together with start\_times if distcrit != 'shore', to allow checking whether structures under construction are

present at a given time point

start\_times A data frame with columns "time" (character string or POSIX of format 'YYYY-

MM-DD HH:MM:SS') and "id", and one row for each structure that is to be used as a proximity criterion for finding candidates. Defines time from which onward the structure is present. Optional; can be provided together with start\_day if distcrit!= 'shore', to allow checking whether structures under construction are

present at a given time point

verbose Logical (default False). If True, writes a summary of each candidate to the

console during "check" runs

#### **Details**

When a DeponsShips object is created using ais.to.DeponsShips, positions are interpolated at 30-minute intervals (ticks). If a ship's position does not change during sequential ticks, these ticks are combined into a pause of the appropriate duration, with a movement speed of 0. However, in some cases, an unmoving ship is actually using its engine to hold position, such as a crew transfer vessel performing a bollard push against a turbine pile, or an offshore supply vessel using a dynamic position system (DPS). Under these circumstances, the ship should emit noise to affect porpoise agents. This function attempts to identify and rewrite such pausing instances in an existing DeponsShips object. A pause is converted into an active stationary position by assigning a non-zero speed and thus noise emission. Note that assigning a speed does not translate into movement, as movement in the model is only derived from position changes, and speed is only used to drive noise calculation.

The intended functionality is to first run the function using 'action = "check"' to return a table of candidate instances. After this has been inspected and thinned as desired by the user, the function is run again using 'action = "replace"' while providing the table as 'candidates', which returns a DeponsShips object where the identified candidate pauses have been replaced with speed values.

No testing criteria (distcrit, landscape, stucture\_locations, start\_day, start\_times) are required for a "replace" run, as the instances provided as 'candidates' are then modified without further checks.

Only ships with type "Other" or "Government/Research" (following the key in Table 1 in MacGillivray & de Jong 2021) are tested, as these categories contain the survey, construction and crew transfer ships that are the primary candidate types. Passenger, recreational, fishing and cargo vessels are assumed to not or rarely use DPS and are omitted. However, the "Other" category also contains vessels that hold position for extended periods without using DPS, such as jack-up rigs and platforms; also, ship type codes provided in AIS data are frequently unreliable. We therefore strongly suggest that the user should carefully scrutinize the candidates table produced in a "check" run, look up vessels by their MMSI code, and remove any false positives from the table before processing it in a "replace" run.

The inserted speed values are 7.4 knots for "Other" and 8 knots for "Government/Research", based on the class reference speeds in MacGillivray & de Jong (2021).

When 'distcrit = "shore"', pause instances are additionally tested against the following criteria: 1) not in a cell (400x400 m) directly adjacent to land, to exclude berthed ships; 2) not in a cell at the map boundary, as ais.to.DeponsShips will create inactive (pausing) placeholder positions at the point of entry if a ship enters the map with a delay after the object's start, or at the point of exit if it leaves before the end of the object's duration; 3) not in the first or last position of the ship's track (same reason).

When candidates are identified based on proximity to a list of structures, a maximum distance of 97.72 m is allowed, based on an estimate of mean AIS positioning error (Jankowski et al. 2021).

#### Value

If 'action = "check"' (default), returns a data frame with columns "route\_number", "ship\_name", "ship\_type", "route\_pos" (position number along route), and "pauses" (number of pauses at this position), with one row for each position that is a candidate for stationary activity based on the selected criteria. If "replace" and a candidates data frame is provided, returns a DeponsShip object where the pauses identified in the data frame have been converted to stationary active status (i.e., a non-zero speed has been assigned).

#### References

MacGillivray, A., & de Jong, C (2021). A reference spectrum model for estimating source levels of marine shipping based on Automated Identification System data. Journal of Marince Science and Engineering, 9(4), 369. doi:10.3390/jmse9040369"

Jankowski, D, Lamm A, & Hahn, A (2021). Determination of AIS position accuracy and evaluation of reconstruction methods for maritime observation data. IFAC-PapersOnLine, 54(16), 97-104. doi:10.1016/j.ifacol.2021.10.079

#### See Also

ais.to.DeponsShips for creation of DeponsShips objects (including calculated speeds) from AIS data

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### **Examples**

make.windfarms

Make wind farm construction scenario

# Description

Produce a hypothetical wind farm construction scenario, specifying the position and timing of individual piling events, as well as the sound source level. All wind farms are assumed to consist of the same number of turbines, laid out in a rectangular grid. The start and end tick (i.e. the number of half-hour intervals since simulation start) is generated based on provided values for the time it required for each piling and the time between piling events.

### Usage

```
make.windfarms(
  area.file,
  area.def,
  n.wf,
  n.turb,
  turb.dist,
 min.wf.dist,
  impact,
  constr.start,
  constr.end,
  constr.time,
  constr.break,
  iterate = 10000,
  verbose = FALSE,
  wf.coords = "random"
)
```

### **Arguments**

area.file Name of the raster file specifying where the wind farms should be constructed.

area.def	Value in area. file for the areas were wind farms can be located
n.wf	Number of wind farms to construct
n.turb	Total number of turbines to construct
turb.dist	Distance between turbines within a wind farm (meters)
min.wf.dist	Minimum distance between wind farms (meters)
impact	Sound source level (dB); sound emitted from turbines during construction, i.e. from tickStart to tickEnd (including both start and end)
constr.start	The tick at which construction of the first turbine starts.
constr.end	The tick at which construction of the very last turbine in the last wind farm ends.
constr.time	The time it takes to construct a single wind turbine (number of ticks).
constr.break	Break between individual pilings within a wind farm, counted in number of half-hour 'ticks'.
iterate	Number of times to try finding a spot for a new wind farm that is sufficiently far from the nearest neighbouring wind farm (>min.wf.dist). The number also defines the number of random positions to search through.
verbose	Logical; whether messages should be printed to console.
wf.coords	Possible location of the south-western corner of the wind farms. Defaults to the text "random", but can also be a data frame with coordinates in the columns x and y.

### Value

data.frame specifying the position of each turbine in a wind farm, along with the start time and end time for pile driving of the turbine foundation and the sound source level during pile driving. Can be exported as a text file and used for controlling DEPONS simulations.

# Note

The parameters constr.start, constr.end, constr.time, and constr.break are truncated to nearest integer value. Construction of wind farms starts in WF001 at tick constr.start. Each turbine foundation is piled over a period of constr.time, followed by a noise-free period of constr.break. Several pile driving operations may take place at the same time, to ensure that the last piling ends before constr.end.

plot, DeponsBlockdyn, missing-method

Plot a DeponsBlockdyn object

### **Description**

Plot population dynamics simulated with DEPONS

### Usage

```
## S4 method for signature 'DeponsBlockdyn,missing'
plot(x, y, dilute = 5, ...)
```

#### **Arguments**

X	DeponsBlockdyn object
у	Not used
dilute	Integer. Plot only one in every 'dilute' values. Defaults to 5, which yields a plot of the first simulated value and one in every five of the following values.
	Optional plotting parameters

### Value

data. frame listing blocks where no animals were counted (returned invisibly)

#### Note

The function returns a data frame with numbers of blocks with no agents.

# **Examples**

```
data("porpoisebdyn")
my.col <- c("red", "darkgreen", "orange")
plot(porpoisebdyn, col=my.col)
legend("bottomright", bty="n", fill=my.col, legend=paste("Block", 0:2))
# Show all data points for small range of x-values
plot(porpoisebdyn, xlim=c(1950, 2050), ylim=c(4850, 5050), type="p", dilute=1, col=my.col)</pre>
```

```
{\it plot}, {\it DeponsDyn}, {\it missing-method} \\ {\it Plot}~a~{\it DeponsDyn}~object
```

### **Description**

Plot population dynamics simulated with DEPONS

# Usage

```
## S4 method for signature 'DeponsDyn,missing'
plot(x, y, dilute = 5, plot.energy = TRUE, plot.legend = TRUE, ...)
```

### **Arguments**

X	DeponsDyn object
У	Not used
dilute	Integer. Plot only one in every 'dilute' values. Defaults to 5, which yields a plot of the first simulated value and one in every five of the following values.
plot.energy	If set to TRUE it plots the amount of energy stored in simulated and in the landscape in addition to the population count
plot.legend	If set to TRUE, a legend is plotted
	Optional plotting parameters

### **Examples**

```
data("porpoisedyn")

# Plot for specific range of years
rg <- c(as.POSIXlt("2011-01-01", tz = "UTC"), as.POSIXlt("2018-12-31", tz = "UTC"))
plot(porpoisedyn, xlim=as.POSIXct(rg), plot.energy=TRUE)

## Not run:
# Read data from default DEPONS simulation directory:
sim.dir <- "/Applications/DEPONS 2.1/DEPONS"
new.sim.name <- get.latest.sim(dir=sim.dir)
new.sim.out <- read.DeponsDyn(fname=paste(sim.dir, new.sim.name, sep="/"))
plot(new.sim.out)

## End(Not run)</pre>
```

```
plot, DeponsRaster, ANY-method
```

Plot a DeponsRaster object

# Description

Plot the values in a DeponsRaster object. Porpoisetracks or other kinds of lines, poits etc. can be drawn on top of the plot by adding

# Usage

```
## S4 method for signature 'DeponsRaster,ANY'
plot(x, y, col, trackToPlot = 1, ...)
```

# Arguments

x DeponsRaster object

y A DeponsTrack object or missing

col	A color palette, i.e.	a vector of n contiguous colors	. Reasonable defaults are

provided.

trackToPlot Integer indicating which track to plot if the DeponsTrack object contains more

than one track. Ignored if y is missing

... Other optional plotting parameters, including 'axes', 'legend', and 'main'.

#### Value

No return value, called for side effects

#### See Also

See method for plot in the raster package for plotting parameters and plot.DeponsTrack for plotting of DeponsRasters cropped to the extent of tracks.

### **Description**

Plot the tracks that ship agents move along in DEPONS.

### Usage

```
## S4 method for signature 'DeponsShips,missing'
plot(x, y, ...)
```

### **Arguments**

Χ	DeponsShips object

y Not used

Optional plotting parameters, including 'col', 'main', 'add.legend', and 'legend.xy' (defaults to 'topright' when add.legend=TRUE)

# Value

No return value, called for side effects

### **Examples**

```
data(shipdata)
plot(shipdata, col=c("red", "green", "blue"))
# convert route coordinate units from 'grid squares' to UTM
data(bathymetry)
out <- summary(bathymetry)</pre>
left <- out[[4]][1]</pre>
bottom <- out[[4]][2]
for (i in 1:3) {
    newroute <- shipdata@routes[[2]][[i]]*400</pre>
    newroute$x <- newroute$x + as.numeric(left)</pre>
    newroute$y <- newroute$y + as.numeric(bottom)</pre>
    shipdata@routes[[2]][[i]] <- newroute</pre>
    }
# Reproject coastline and clip to size of Kattegat landscape
library(sp)
data(bathymetry)
data(coastline)
coastline_sf <- sf::st_as_sf(coastline)</pre>
coastline2 <- sf::st_transform(coastline_sf, crs(bathymetry))</pre>
bbox <- bbox(bathymetry)</pre>
clip.poly <- make.clip.poly(bbox, crs(bathymetry))</pre>
plot(shipdata, col=c("red", "green", "blue"), add=TRUE, add.legend=TRUE)
plot(clip.poly, add=TRUE)
```

# Description

Plot the coordinates in a movement track simulated with DEPONS.

### Usage

```
## S4 method for signature 'DeponsTrack,missing'
plot(x, y, trackToPlot = 1, add = FALSE, ...)
```

Defaults to 1

# **Arguments**

x DeponsTrack object
 y Not used
 trackToPlot Integer; indicates which track to plot if there is more than one track in the object.

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add Logical, whether to add the track to an existing plot one animal was tracked

during the simulation.

... Optional plotting parameters

#### Value

No return value, called for side effects

### **Examples**

```
data(porpoisetrack)
data("porpoisetrack")
plot(porpoisetrack)
```

porpoisebdyn

Simulated porpoise population dynamics

### **Description**

An object of class DeponsBlockdyn with output from a DEPONS simulation based on the North Sea landscape, using a landscape divided into two blocks. Numbers of animals are counted per block.

### **Format**

DeponsBlockdyn

### See Also

DeponsBlockdyn-class, porpoisedyn

porpoisedyn

Simulated porpoise population dynamics

### **Description**

An object of class DeponsDyn with output from a DEPONS simulation based on the Kattegat land-scape, assuming that the simulation represents the period 2010-01-01 onward in the real world. Number of animals and energy availability is recorded for the entire landscape.

#### **Format**

DeponsDyn

# See Also

DeponsDyn-class, porpoisebdyn

porpoisetrack

Simulated porpoise track

### **Description**

An object with five elements: title, landscape, simtime, crs, and tracks. The crs stores information about the map projection used ("+proj=utm +zone=32 +datum=WGS84 +units=m +no\_defs"). The tracks element is a list of objects of class SpatialPointsDataFrame, each ofwhich corresponds to one simulated animal. simtime is the simulation date.

#### **Format**

DeponsTrack

### See Also

DeponsTrack-class

read.DeponsBlockdyn

Reading simulated population count for blocks

### **Description**

Function for reading DEPONS simulation output with number of animals per block for each time step.

### Usage

```
read.DeponsBlockdyn(
   fname,
   title = "NA",
   landscape = "NA",
   simtime = "NA",
   timestep = 30,
   startday = "2010-01-01",
   tz = "UTC"
)
```

# Arguments

fname Name of the file (character) that contains movement data generated by DE-

PONS. The name includes the path to the directory if this is not the current

working directory.

title Optional character string giving name of simulation

landscape The landscape used in the simulation

read.DeponsDyn 33

simtime	Optional text string with date of simulation (format: yyyy-mm-dd). If not provided this is obtained from name of input file
timestep	Time step used in the model, in minutes. Default 30 minutes
startday	The start of the period that the simulation represents, i.e. the real-world equivalent of 'tick 1' (character string of the form 'yyyy-mm-dd', or POSIXIt). Default "2010-01-01"
tz	Time zone. In DEPONS times are generally assumed to be in "UTC" (Coordinated Universal Time).

### Value

DeponsBlockdyn object

### See Also

See DeponsBlockdyn-class for details on what is stored in the output object and read. DeponsParam for reading the parameters used in the simulation.

# **Examples**

read.DeponsDyn

Reading DEPONS simulation output

### **Description**

Function for reading simulation output produced by DEPONS.

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### Usage

```
read.DeponsDyn(
  fname,
  title = "NA",
  landscape = "NA",
  simtime = "NA",
  startday = "2010-01-01",
  timestep = 30,
  tz = "UTC"
)
```

# Arguments

fname	Name of the file (character) that contains number of animals for each time step during the simulation, along with their energy and the amount of food in the landscape. The name includes the path to the directory if this is not the current working directory.
title	Optional character string giving name of simulation
landscape	The landscape used in the simulation
simtime	Optional character string with the date and time when the simulation finished (format yyyy-mm-dd). If not provided this is obtained from name of input file
startday	The start of the period that the simulation represents, i.e. the real-world equivalent of 'tick 1' (character string of the form 'yyyy-mm-dd', or POSIXIt). Default "2010-01-01"
timestep	Time step used in the model, in minutes. Default 30 minutes.
tz	Time zone. In DEPONS times are generally assumed to be in "UTC" (Coordinated Universal Time).

# Value

DeponsDyn object containing simulation output

### See Also

See DeponsDyn-class for details on what is stored in the output object and as.data.frame for converting from data frame.

```
## Not run:
dyn.file <- "/Applications/DEPONS 2.1/DEPONS/Statistics.2020.Sep.02.20_24_17.csv"
file.exists(dyn.file)
porpoisedyn <- read.DeponsDyn(dyn.file, startday=as.POSIXlt("2010-01-01", tz = "UTC"))
porpoisedyn
## End(Not run)</pre>
```

read.DeponsDynBatch

Read and merges DEPONS Batchmap and Statistics Files

# Description

Reads batch map files and statistics files from a specified directory and returns a list of 'DeponsDyn' objects and parameter values.

# Usage

```
read.DeponsDynBatch(
  dir,
  par,
  title = "NA",
  landscape = "NA",
  simtime = "NA",
  startday = "NA",
  timestep = 30,
  tz = "UTC"
)
```

### **Arguments**

dir	Character string specifying the directory path containing the 'Batchmap' and 'Statistics' files.
par	Character vector specifying the column names to extract from the batch map file for each run. #' These parameters are then stored in the 'Parameters' list.
title	Optional character string
landscape	Character string. Name of the simulation landscape. Default is "NA".
simtime	Optional character string with the date and time when the simulation finished (format yyyy-mm-dd).
startday	The start of the period that the simulation represents, i.e. the real-world equivalent of 'tick 1' (character string of the form 'yyyy-mm-dd', or POSIXIt)
timestep	Time step used in the model, in minutes. Defaults to 30 in DEPONS.
tz	Timezone.

#### Value

A list of 'DeponsDyn' objects and parameter values associated with run id

```
## Not run:
# Specify the directory containing Batchmap and Statistics files
dir_path <- "path/to/batchdata"</pre>
```

36 read.DeponsParam

```
# Specify parameters to extract from Batchmap files
par <- c("parameter1", "parameter2")

# Run the function
results <- read.DeponsBatch(
    dir = dir_path,
    par = par,
    startday = "2010-01-01"
)

## End(Not run)</pre>
```

read.DeponsParam

Read simulation parameters

### **Description**

Read the parameters that were used for running a specific DEPONS simulation

#### Usage

```
read.DeponsParam(fname)
```

### **Arguments**

fname

Name of the XML file (character) that contains the parameter list used for running a DEPONS simulation. The name includes the path to the directory if this is not the current working directory.

#### **Details**

The parameter file can be generated from within DEPONS by pressing the 'Save' icon after modifying the user settings on the 'Parameters' tab within the main DEPONS model window. See TRACE document for details regarding the parameters in the model: https://github.com/jacobnabe/DEPONS. It is strongly recommended that the parameter list is stored with the simulation output.

#### Value

Data frame containing all parameters used in a specific simulation

```
## Not run:
# Parameters read from file created by DEPONS run in interactive mode
the.file <- "/Applications/DEPONS 2.1/DEPONS/DEPONS.rs/parameters.xml"
pfile <- read.DeponsParam(the.file)
## End(Not run)</pre>
```

read.DeponsRaster 37

read.DeponsRaster	Reading DEPONS raster files
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#### **Description**

Function for reading raster files that have been used in DEPONS simulations. DEPONS rasters define amount of food available for simulated animals, spatial distribution of food patches, bathymetry, and distance to coast (dtc). The 'blocks' raster enables the user to count animals in specific parts of the landscape during simulations. See Nabe-Nielsen et al. (2018) for details regarding these files. In DEPONS 2.0 the salinity raster file was introduced; see TRACE document for details: https://github.com/jacobnabe/DEPONS

## Usage

```
read.DeponsRaster(fname, type = "NA", landscape = "NA", crs = "NA")
```

#### **Arguments**

type The kind of data stored in the raster; c('food', 'patches', 'bathymetry', 'dtc',

'salinity', 'blocks').

landscape Identifier for the landscape used in the DEPONS simulations; typically set to

'North Sea'.

crs CRS-object providing the map projection (see CRS).

#### Value

Returns a DeponsRaster object. The object inherits slots from the "RasterLayer" class, including "title", which is used for storing the file name.

#### References

Nabe-Nielsen, J., van Beest, F. M., Grimm, V., Sibly, R. M., Teilmann, J., & Thompson, P. M. (2018). Predicting the impacts of anthropogenic disturbances on marine populations. Conservation Letters, 11(5), e12563. doi:10.1111/conl.12563

#### See Also

DeponsRaster-class

38 read.DeponsTrack

read.DeponsShips	Read DEPONS ship files
------------------	------------------------

## **Description**

Function for reading the json-files that are used for controlling how ship agents behave in DEPONS. Ships move along pre-defined routes in 30-min time steps. The routes are defined by the fix-points provided in the json file, and the geographic projection is assumed to match that of the landscape.

#### Usage

```
read.DeponsShips(fname, title = "NA", landscape = "NA", crs = as.character(NA))
```

## **Arguments**

fname Name of the file (character) where ship routes and ships	s are defined.
--	----------------

title Optional character string with the name of the simulation

landscape Optional character string with the landscape used in the simulation

crs Character, coordinate reference system (map projection)

## Value

Returns an object with the elements title landscape, crs, routes and ships.

#### See Also

```
ais.to.DeponsShips, write.DeponsShips
```

${\sf read.DeponsTrack}$	Reading DEPONS track files

#### **Description**

Function for reading movement tracks produced by DEPONS. These describe movements of simulated animals within the simulation landscape, where the positions after each 30-min time step are provided using the coordinate reference system that were used for generating these landscapes. See van Beest et al. (2018) and Nabe-Nielsen et al. (2013) for details regarding how these files were generated as a balance between correlated random walk behaviour and spatial memory behaviour, which allows animals to return to previously visited food patches.

read.DeponsTrack 39

#### Usage

```
read.DeponsTrack(
  fname,
  title = "NA",
  landscape = "NA",
  simtime = "NA",
  crs = as.character(NA),
  tz = "UTC"
)
```

#### **Arguments**

fname	Name of the file (character) that contains movement data generated by DE-PONS. The name includes the path to the directory if this is not the current working directory.
title	Optional character string giving name of simulation
landscape	Optional character string with the landscape used in the simulation
simtime	Character sting with date of simulation (format yyyy-mm-dd). If not provided this is obtained from name of input file
crs	Character, coordinate reference system (map projection)
tz	Time zone used in simulations. Defaults to UTC. #'

#### Value

Returns a DeponsTrack object with the elements title, simtime, crs, and tracks. The date is extracted from input data if not provided explicitly and stored as a POSIX1t object. The element tracks is a list of objects of class SpatialPointsDataFrame, each of which corresponds to one simulated animal (several animals can be tracked in one simulation).

## **Examples**

```
data(porpoisetrack) # Load data for use in example

# Use standard DEPONS coordinate reference system / map projection:
the.crs <- "+proj=laea +lat_0=52 +lon_0=10 +x_0=4321000 +y_0=3210000
    +datum=WGS84 +units=m +no_defs"

## Not run:
one.fname <- "~/Applications/DEPONS/
    RandomPorpoise.2020.Jul.31.09_43_10.csv"

porpoisetrack <- read.DeponsTrack(one.fname, title="Track simulated using DEPONS 2.0",
    crs=the.crs)

## End(Not run)

# Plot the first of the simulated tracks
plot(porpoisetrack)</pre>
```

read.DeponsTrackBatch Read and Process DEPONS Batchmap and Statistics Files

## **Description**

Reads batch map files and random porpoise files from a specified directory, merges them for each run, and returns a list of 'DeponsTrack' objects and parameter values

## Usage

```
read.DeponsTrackBatch(
    dir,
    par,
    title = "NA",
    landscape = "NA",
    simtime = "NA",
    crs = as.character(NA),
    tz = "UTC"
)
```

## **Arguments**

dir	Character string specifying the directory path containing the 'Batchmap' and 'RandomPorpoise' files
par	Character vector specifying the column names to extract from the batch map file for each run. These parameters are then stored in the 'Parameters' list
title	Optional character string giving name of simulation
landscape	Character string. Name of the simulation landscape
simtime	Character sting with date of simulation (format yyyy-mm-dd). If not provided this is obtained from name of input file
crs	Character, coordinate reference system (map projection)
tz	Time zone used in simulations. Defaults to UTC/GMT

#### Value

A list of 'DeponsTrack' objects and parameter values associated with run id

# **Examples**

```
## Not run:
# Specify the directory containing Batchmap and Statistics files
dir_path <- "path/to/batchdata"

# Specify parameters to extract from Batchmap files
par <- c("parameter1", "parameter2")</pre>
```

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```
# Run the function
results <- read.DeponsBatch(
   dir = dir_path,
   par = par,
   crs = "+proj=longlat +datum=WGS84"
)
## End(Not run)</pre>
```

routes

Get or define routes in DeponsShips objects

#### **Description**

Get or define routes in DeponsShips objects

# Usage

```
## $4 method for signature 'DeponsShips'
routes(x)
## $4 replacement method for signature 'DeponsShips'
routes(x) <- value</pre>
```

## **Arguments**

x Object of class DeponsShips

value

list with one named element per shipping route. Each element is a data frame with the variables x, y, speed, and 'pause' which define the coordinates of the fix-points on the shipping routes and the speeds that ships have after passing the fix point and until reaching the next fix point. The variable 'pause' instructs ships about how many minutes to wait before continuing to move.

#### Note

The unit of 'speed' is knots.

#### See Also

ships

ships

shipdata

Ships on example routes through the Kattegat

#### **Description**

The routes of fifteen ships of different types in the Kattegat during a period of 15 days. The fix points that define the routes use the UTM zone 32 projection (CRS = "+proj=utm +zone=32 +units=m +no\_defs +datum=WGS84"; EPSG:32632; see https://epsg.io/32632).

#### **Format**

DeponsShips object

#### See Also

[DeponsShips-class]

ships

Get or define ships in DeponsShips objects

## Description

Get or define ships in DeponsShips objects

## Usage

```
## $4 method for signature 'DeponsShips'
ships(x)
ships(x) <- value</pre>
```

## **Arguments**

Χ

Object of class DeponsShips

value

data frame with the 'name', 'type', 'length', and 'route' of ships to be simulated, as well as 'tickStart' and 'tickEnd' defining when the ships are to be included in simulations. 'route' is one of the shipping routes defined in the DeponsShips object.

#### See Also

routes

## **Examples**

```
data(shipdata)
ships(shipdata)
```

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startday

Get or set start date for simulation

## **Description**

Get or set start date for simulation Get or set start date for simulation

# Usage

```
## S4 method for signature 'DeponsBlockdyn'
startday(x)
## S4 method for signature 'DeponsDyn'
startday(x)
## S4 replacement method for signature 'DeponsBlockdyn'
startday(x) <- value
## S4 replacement method for signature 'DeponsDyn'
startday(x) <- value</pre>
```

#### **Arguments**

x Object of class DeponsDyn

value POSIXIt or character string of the form 'yyyy-mm-dd'

## **Details**

The start date indicates the start of the period that the simulation is supposed to represent.

The start date indicates the start of the period that the simulation is supposed to represent.

#### Note

The assignment of a new start time is currently quite time consuming.

Summary-methods

Summary

## **Description**

Summarizes different kinds of objects created based on output from the DEPONS model

44 tick.to.time

## Usage

```
## S4 method for signature 'DeponsBlockdyn'
summary(object)

## S4 method for signature 'DeponsDyn'
summary(object)

## S4 method for signature 'DeponsRaster'
summary(object)

## S4 method for signature 'DeponsShips'
summary(object)

## S4 method for signature 'DeponsTrack'
summary(object)
```

#### **Arguments**

object Depons\* object

#### **Details**

The summary method is available for DeponsTrack-class, DeponsDyn-class, DeponsRaster-class, and DeponsBlockdyn-class-objects.

#### Value

list summarizing the DeponsBlockdyn object table summarizing the DeponsBlockdyn object list summarizing the DeponsRaster object list summarizing the DeponsTrack object

tick.to.time

Convert tick number to time object

# Description

Converts the number of ticks since the start of the simulation to a specific date while taking into account that DEPONS assumes that there are 360 days in a simulation year.

#### Usage

```
tick.to.time(tick, timestep = 30, origin = "2010-01-01", tz = "UTC", ...)
```

time.to.tick 45

## **Arguments**

tick	Numeric, or numeric vector; tick number
timestep	Numeric; length of each simulation time step, in minutes. Defaults to 30 minutes.
origin	Character. The first day of the period that the simulation represents, format: 'yyyy-mm-dd'.
tz	Character. Valid time zone code (default UTC).
	Optional parameters

# Value

```
object of class as.POSIXlt
```

## Note

The function assumes that there are 30 days in each month, except in January, February and March with 31, 28 and 31 days, respectively.

#### See Also

time.to.tick is the inverse of this function, converting dates to ticks

time.to.tick Convert date to tick number
--

# Description

Convert a date to the number of ticks since simulation start while taking into account that DEPONS assumes that there are 360 days in a simulation year.

## Usage

```
time.to.tick(time, timestep = 30, origin = "2010-01-01", tz = "UTC", ...)
```

# Arguments

time	Character, or character vector, of the form 'YYYY-MM-DD' (or 'YYYY-MM-DD HH:MM:SS'), or equivalent POSIX object. Date(s) to be converted to ticks.
timestep	Numeric (default 30). Length of each simulation time step in minutes.
origin	Character of the form 'YYYY-MM-DD' or equivalent POSIX object (default "2010-01-01"). Start date of simulation.
tz	Character. Valid time zone code (default UTC).
	Optional parameters.

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#### **Details**

Times are rounded down to the current 30-minute interval during conversion. The function assumes that there are 30 days in each month, except in January, February and March with 31, 28 and 31 days, respectively. Provided dates that fall on days that are not accommodated (February 29, and the 31st day of the months May, July, August, October, and December) are returned as NA.

The function may be used to, e.g., convert recorded piling dates to ticks for use in wind farm scenarios (see make.windfarms for construction of hypothetical scenarios from parametric inputs).

#### Value

Numeric vector of tick numbers.

#### See Also

tick. to. time is the inverse of this function, converting ticks to dates

#### **Examples**

title<-

Get or set the title of Depons\* objects

#### **Description**

Get or set the title of Depons\* objects

## Usage

```
## S4 replacement method for signature 'DeponsTrack'
title(x) <- value

## S4 replacement method for signature 'DeponsDyn'
title(x) <- value

## S4 replacement method for signature 'DeponsShips'
title(x) <- value

## S4 method for signature 'DeponsTrack'
title(x, value)

## S4 method for signature 'DeponsDyn'
title(x, value)

## S4 method for signature 'DeponsShips'
title(x, value)</pre>
```

#### **Arguments**

x Object of class DeponsTrack, DeponsDyn, DeponsBlockdyn or DeponsShipsvalue Character string

```
write, DeponsShips-method
```

Write DEPONS ship files

# Description

Function for writing a json-file for controlling how ship agents behave in DEPONS. Ships move along pre-defined routes in 30-min time steps. The routes are defined by the fix-points provided in the json file, and the geographic projection is assumed to match that of the landscape. The projection is not stored as part of the json file.

# Usage

```
## S4 method for signature 'DeponsShips'
write(x, file)
```

#### **Arguments**

x Name of the DeponsShips object to be exported

file Name of the output file (character)

# Value

No return value, called for side effects

# Note

The exported json file is intended for use in DEPONS 2.3 or later (released July 2022) where the sound pressure level (SPL) is calculated within DEPONS based on ship type, ship length and speed.

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