# Package 'AMISforInfectiousDiseases'

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**Title** Implement the AMIS Algorithm for Infectious Disease Models

Version 0.1.0

**Description** Implements the Adaptive Multiple Importance Sampling (AMIS) algorithm, as described by Retkute et al. (2021, <doi:10.1214/21-AOAS1486>), to estimate key epidemiological parameters by combining outputs from a geostatistical model of infectious diseases (such as prevalence, incidence, or relative risk) with a disease transmission model. Utilising the resulting posterior distributions, the package enables forward projections at the local level.

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URL https://github.com/drsimonspencer/AMISforInfectiousDiseases-dev

BugReports https://github.com/drsimonspencer/AMISforInfectiousDiseases-dev/issues

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amis

Run the AMIS algorithm to fit a transmission model to a map

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## **Description**

This implements the AMIS algorithm as described in Retkute et al. (2021). Each iteration of the algorithm produces a set of parameters from a proposal distribution (the prior in the first iteration). For each parameter set, a simulation is run from the transmission model. Then, each preceding simulation is weighted at each location according to the distribution of prevalences (or likelihood function) at that location. A Gaussian mixture model is then fitted to the parameter samples with weights averaged over the active locations (ie locations that have yet to reach the effective sample size target). This Gaussian mixture informs the proposal for the next iteration. The algorithm continues until every location has reached the ESS target, or the maximum number of iterations is reached.

### Usage

```
amis(
  prevalence_map,
  transmission_model,
  amis_params = default_amis_params(),
  seed = NULL,
  output_dir = NULL,
  initial_amis_vals = NULL
)
```

## **Arguments**

prevalence\_map For a single timepoint, "prevalence\_map" can be an  $L \times M$  matrix or data frame containing samples from a geostatistical model, where L is the number of locations and M the number of samples per location.

> If there are multiple timepoints and/or a parametric likelihood function is to be used, "prevalence\_map" must be a list with T elements, one for each timepoint  $t=1,\ldots,T$ . Each element must itself be a list with the following objects:

data An  $L \times M$  matrix as above

likelihood (optional) A function taking arguments:

- data: A vector of length  $M_l$ , where  $M_l$  is the number of samples from a geostatistical model for location l or the number of likelihood parameters:
- sim\_prev: A numeric value for a prevalence simulated from the transmission model;
- log: Logical indicating if calculations are to be performed on log scale (specified in "amis\_params", see below).

The function likelihood must return a numeric value representing the (log-)likelihood of observing a simulated prevalence given the data from a particular location.

The location names are inherited from rownames(prevalence\_map) if "prevalence\_map" is a matrix, and from rownames(prevalence\_map[[1]]\$data) if "prevalence\_map" is a list.

If likelihood is not specified, then it is assumed that the data consist of samples from a geostatistical model and a nonparametric method is used. The nonparametric method to be used is specified in "amis\_params" using the options breaks, delta, or sigma (see "amis\_params").

#### transmission\_model

A function taking arguments:

- seeds: a vector of n seeds;
- params: an  $n \times d$  matrix of parameter vectors;
- n\_tims: number of time points.

This function must return an  $n \times T$  **matrix** of prevalences (it must be a matrix even when T=1). The vector seeds will be the vector of indexes of the simulated samples. If n\_samples new samples are drawn within each iteration of the AMIS algorithm, then the vector seeds will be 1:n\_samples at the first iteration, (n\_samples+1):(2\*n\_samples) at the second iteration, and so on.

prior

A list containing the functions dprior and rprior (density and random number generator, respectively). The two arguments of dprior must be:

- a d-length vector of transmission model parameters; and
- a logical log to indicate whether to calculate log-density or not.

The only argument of rprior must be a single integer n that determines the number of samples to draw. rprior must produce an  $n \times d$  matrix of parameters even when d=1. Parameter names are inherited from the colnames of the output of rprior.

amis\_params

A list containing control parameters for the AMIS algorithm (default\_amis\_params() returns the default values):

n\_samples Number of new samples drawn within each AMIS iteration. Default to 500

target\_ess Target effective sample size. Default to 500.

max\_iters Maximum number of AMIS iterations. Default to 12.

boundaries A vector of length two with the left and right boundaries for prevalences. Default to c(0,1). If, for instance, left boundary is zero and there is no right boundary, set boundaries = c(0, Inf).

boundaries\_param If specified, it should be a  $d \times 2$  matrix with the lower and upper boundaries for the d transmission model parameters. Default to NULL.

log Logical indicating if calculations are to be performed on log scale. Default to TRUE.

delete\_induced\_prior Logical indicating whether the induced prior density is to be deleted in the update of weights. Default to FALSE.

mixture\_samples Number of samples used to represent the weighted parameters in the mixture fitting.

df Degrees of freedom in the t-distributions, used to yield a heavy tailed proposal. Default to 3.

q Parameter (between 0 and 1) controlling how the weights are calculated for active locations. Default to 0. See Details below.

delta Optional smoothing parameter if uniform kernel (default) is used. Default to 0.01.

sigma Optional smoothing parameter if Gaussian kernel is used. Default to NULL.

breaks Optional vector specifying the breaks for the histogram. Default to NULL. For finite boundaries, the first and last entries of breaks must be equal to the left and right boundaries, respectively. For non-finite boundaries, ensure that the range of breaks includes any possible prevalence value.

Uniform kernel is the default method for the density estimator of the likelihood. If sigma is provided, then Gaussian kernel will be used instead. If breaks is provided, then histogram-based method will be the nonparametric method being used. Note that if likelihood is provided in prevalence\_map, then a parametric method will be implemented.

seed

Optional single value interpreted as an integer. It is the seed for the random number generator for the AMIS algorithm. This is not the same as the seeds argument passed to "transmission\_model".

output\_dir

A string specifying the local directory where to save outputs after each iteration of the algorithm. At the end of the string, use the correct path separator for your machine's operating system. If the directory is specified, the outputs will be saved in a file called 'amis\_output.rds'. Default to NULL (i.e. outputs are not saved in a local directory).

#### initial\_amis\_vals

Optional list of intermittent outputs from a previous run (where at least one iteration was successful). These outputs can be saved by specifying the directory "output\_dir".

#### **Details**

The average weight of parameter vectors for the set of active locations at iteration  $i(A_i)$  has weights determined by how far the effective sample size for location  $l(ESS_l^i)$  is from the target  $(ESS^R)$ :

$$\bar{w}_{j}^{i} = \frac{\sum_{l \in A_{i}} \left( \mathsf{ESS}^{R} - \mathsf{ESS}_{l}^{i} \right)^{q} \hat{w}_{lj}^{i}}{\sum_{l \in A_{i}} \left( \mathsf{ESS}^{R} - \mathsf{ESS}_{l}^{i} \right)^{q}}, \qquad q \in [0, 1].$$

If q=0 (default), the simple average of individual weights will be calculated. If q>0, more weight will be assigned to locations with low ESS.

#### Value

A list of class amis. If the algorithm completed I iterations, it simulated a total of  $N = I \times n_s$  amples, and therefore the list returned by amis() will contain:

seeds An N-length vector with the simulation seeds that were used.

param An  $N \times d$  matrix with the d-dimensional transmission model parameters simulated by the algorithm.

simulated\_prevalences An  $N \times T$  matrix with the simulated prevalences, where T is the number of timepoints.

weight\_matrix An  $N \times L$ , where L is the number of locations.

likelihoods A  $T \times L \times N$  array with the likelihood of observing a simulated prevalence in each location at each time.

ess An L-length vector with the final effective sample size (ESS) for each location.

prevalence\_map List with the prevalence map supplied by the user.

locations\_with\_no\_data Vector indicating which locations have no data at any time point.

components A list of the mixture components of all iterations, containing:

- G: number of components in each iteration;
- probs: the mixture weights;
- Mean: the locations of the components;
- Sigma: the covariance matrices of the components.

components\_per\_iteration A list with the mixture components at each iteration. This object is used in plot\_mixture\_components().

ess\_per\_iteration An  $L \times I$  matrix with with the ESS for each location after each iteration.

prior\_density An N-length vector with the density function evaluated at the simulated parameter values.

amis\_params List supplied by the user.

evidence A list containing an estimate of the log model evidence and corresponding log variance of this estimate for both the full likelihood model (product over all locations), and for each location individually.

#### References

Retkute, R., Touloupou, P., Basanez, M. G., Hollingsworth, T. D., Spencer, S. E. (2021). *Integrating geostatistical maps and infectious disease transmission models using adaptive multiple importance sampling*. The Annals of Applied Statistics, 15(4), 1980-1998. doi:10.1214/21AOAS1486.

## **Examples**

```
# Define simple "transmission" model where prevalence equals first parameter
transmission_model_identity <- function(seeds, parameters, n_tims=1) {</pre>
  return(matrix(parameters[,1], ncol=1))
# Generate samples for prevalence map with 3 locations given by B(2,1), B(1,1)=Uniform, B(1,2).
set.seed(123)
L <- 3
         # Number of locations
M <- 500 # Number of map samples
prevalence_map <- matrix(NA, L, M)</pre>
for (1 in 1:L) {
  prevalence_map[1,] <- rbeta(M, max(1,l-1), max(1,3-1))
rownames(prevalence_map) <- c("Here", "There", "Somewhere else")</pre>
# Define 2D exponential prior
rprior <- function(n) {</pre>
  params <- matrix(NA, n, 2)</pre>
  colnames(params) <- c("a","b")</pre>
  params[,1] <- rexp(n)</pre>
  params[,2] <- rexp(n)</pre>
  return(params)
}
dprior <- function(x, log=FALSE) {</pre>
  if (log) {
    return(sum(dexp(x, log=TRUE)))
  } else {
    return(prod(dexp(x)))
prior <- list(rprior=rprior,dprior=dprior)</pre>
# Run AMIS with default control parameters
amis_params <- default_amis_params()</pre>
output <- amis(prevalence_map, transmission_model_identity, prior, amis_params, seed=1)</pre>
print(output)
summary(output)
original_par <- par(no.readonly = TRUE)</pre>
par(cex.lab=1.5, cex.main=1.5, mar=c(5,4.5,4,2)+0.1)
par(mfrow=c(1,2))
plot_mixture_components(output, what = "uncertainty", cex=3)
plot_mixture_components(output, what = "density", nlevels=200)
par(mfrow=c(3,3))
plot(output, what = "a", type="hist", locations=1:L, breaks=100)
plot(output, what = "b", type="hist", locations=1:L, breaks=100)
plot(output, what = "prev", type="hist", locations=1:L, time=1, breaks=100)
```

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calculate\_summaries

Calculate summaries of weighted statistics

### **Description**

Calculate summaries of weighted statistics

### Usage

```
calculate_summaries(
    x,
    what = "prev",
    time = 1,
    locations = NULL,
    alpha = 0.05,
    exceedance_prob_threshold = 0.35
)
```

### **Arguments**

x The output from the function amis().

what What statistic should be calculated the summaries from. It must be either "prev"

or the name of one of the model parameters. Default to "prev".

time Time point. Only used if "what" is set to "prev".

locations Integer vector or location names identifying locations where summaries should

be calculated for. If not specified, summary statistics of all locations will be

provided.

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alpha

Numeric value between 0 and 1. Calculations are for the (alpha/2, 1-alpha/2)% quantiles.

exceedance\_prob\_threshold

Numeric value. Default to 0.35, i.e. the probability that the statistic of interest (e.g. prevalence) is higher than 0.35.

## **Details**

For illustrative examples, see amis().

## Value

A list with mean, median, and quantiles of the weighted distribution.

default\_amis\_params

Produce list containing the default AMIS parameters

# Description

For description of AMIS parameters, see argument amis\_params in amis().

## Usage

```
default_amis_params()
```

## Value

List containing the default AMIS parameters.

plot.amis

Plot histogram or credible interval of weighted distributions given a model fitted by amis()

## **Description**

Plot histogram or credible interval of weighted distributions given a model fitted by amis()

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### Usage

```
## S3 method for class 'amis'
plot(
  х,
 what = "prev",
  type = "hist",
  locations = 1,
  time = 1,
 measure_central = "mean",
  order_locations_by = NULL,
  display_location_names = FALSE,
  alpha = 0.05,
  breaks = 500,
  cex = 1,
  1wd = 1,
  xlim = NULL,
 main = NULL,
 xlab = NULL,
 ylab = NULL,
)
```

## **Arguments**

The output from the function amis().

what What posterior distribution should be plotted. It can be "prev" (default) for

plotting prevalences, or one of the parameter names.

type Type of plot. It can be "hist" (default) for histogram, or "CI" for credible

intervals

locations Integer vector or location names identifying locations the plots are made for.

Default to 1 (first location).

time Integer index identifying the timepoint. Default to 1.

measure\_central

Measure of central tendency for credible interval plots. It can be "mean" (default) or "median".

order\_locations\_by

How the credible intervals of multiple locations should be ordered. If NULL (default), locations are displayed according to the argument "locations". Otherwise, it must be either "prev" or one of the parameter names, and then the locations are ranked by the corresponding measure of central tendency.

display\_location\_names

Logical indicating whether location names are to be shown or not in credible interval plots. Default to FALSE.

alpha

Numeric value between 0 and 1 indicating the endpoints of the credible intervals, which are evaluated at (alpha/2, 1-alpha/2)% quantiles. Default (0.05) will create 95% credible intervals.

breaks	Argument passed to wtd.hist() for histogram plots. Default to 500.
cex	Argument passed to plots of credible intervals. Default to 1.
lwd	Argument passed to plots of credible intervals. Default to 1.
xlim	The x limits of the plots. For for credible intervals of multiple statistics (i.e. length(what)>1), it must be either NULL or a list with the x limits for each statistic. Default to NULL.
main	Title for the plot.
xlab	Lable for the x axis.
ylab	Lable for the y axis.
	Other graphical parameters passed to wtd.hist().

## **Details**

For illustrative examples, see amis().

## Value

A plot.

```
{\it Plot\_mixture\_components} \\ {\it Wrapper function for plot.Mclust()}
```

# Description

Wrapper function for plot.Mclust()

# Usage

```
plot_mixture_components(
    x,
    what = "uncertainty",
    iteration = NULL,
    datapoints = "proposed",
    main = NULL,
    xlim = NULL,
    ylim = NULL,
    ...
)
```

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# Arguments

X	The output from the function amis().
what	A string specifying the type of plot requested:
	"uncertainty" A plot of classification uncertainty (default)
	"density" A plot of estimated density
	"BIC" A plot showing BIC values used to choose the number of components
iteration	Integer indicating which iteration the plot should be about. If NULL (default), the plot will be for the final iteration. See more details in plot.Mclust().
datapoints	A string specifying what the datapoints should represent in the plot of classification uncertainty:
	"proposed" datapoints will represent the samples simulated from the mixture. The colours indicate which mixture components the samples were simulated from.
	"fitted" datapoints will show the samples that the mixture model was fitted to, i.e. weighted samples from the previous iteration. The colour of a datapoint indicates the most likely mixture component the sample belongs to.
main	Title of the plot. If NULL, the default title will be displayed. Set to NA for omitting title.
xlim	The x limits of the plots. Default to NULL
ylim	The y limits of the plots. Default to NULL.
• • •	Other arguments to match the plot.Mclust() function.

## **Details**

For illustrative examples, see amis().

# Value

A plot for model-based clustering results.

print.amis

Print method for object of class amis

# Description

Print method for object of class amis

# Usage

```
## S3 method for class 'amis' print(x, ...)
```

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## **Arguments**

x The output from the function amis().

... Other arguments to match the generic print() function

## **Details**

For illustrative examples, see amis().

#### Value

Brief description of data and model specifications used to run amis().

sample\_parameters Sample parameters from their weighted distributions given a model fitted by amis()

## Description

Sample parameters from their weighted distributions given a model fitted by amis()

## Usage

```
sample_parameters(x, n_samples = 200, locations = 1)
```

# Arguments

The output from the function amis().

n\_samples Number of samples to draw. Default to 200.locations Integer identifying the locations. Default to 1.

## **Details**

For illustrative examples, see amis().

### Value

Matrix with parameter values and corresponding prevalences for each location.

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summary.amis

Summary method for object of class amis

# Description

Summary method for object of class amis

# Usage

```
## S3 method for class 'amis'
summary(object, ...)
```

# Arguments

object The output from the function amis().

... Other arguments to match the generic summary() function

## **Details**

For illustrative examples, see amis().

### Value

Summary statistics of the fitted model.

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